

Assignment 4 (Duu 10/4).

§3.4 1)
$$\left[\begin{array}{cccc|c} 2 & 4 & 6 & 4 & b_1 \\ 2 & 5 & 7 & 6 & b_2 \\ 2 & 3 & 5 & 2 & b_3 \end{array} \right] \longrightarrow \left[\begin{array}{cccc|c} 2 & 4 & 6 & 4 & b_1 \\ 0 & 1 & 1 & 2 & b_2 - b_1 \\ 0 & -1 & -1 & -2 & b_3 - b_1 \end{array} \right]$$

$$\longrightarrow \left[\begin{array}{cccc|c} 2 & 4 & 6 & 4 & b_1 \\ 0 & 1 & 1 & 2 & b_2 - b_1 \\ 0 & 0 & 0 & 0 & b_2 + b_3 - 2b_1 \end{array} \right]$$

- $A\vec{x} = \vec{b}$ has a solution when $b_2 + b_3 - 2b_1 = 0$.
- The column space of A is a plane (the plane spanned by $\begin{bmatrix} 2 \\ 2 \\ 2 \end{bmatrix}$ and $\begin{bmatrix} 4 \\ 5 \\ 3 \end{bmatrix}$).

Alternately, it is the plane $b_2 + b_3 - 2b_1 = 0$

- The nullspace of A is the nullspace of U .

It is spanned by special solutions s_1 and s_2 .

$$s_1 = \begin{bmatrix} a \\ b \\ 1 \\ 0 \end{bmatrix}, \quad s_2 = \begin{bmatrix} c \\ d \\ 0 \\ 1 \end{bmatrix}$$

$$2a + 4b + 6 = 0$$

$$b + 1 = 0$$

$$b = -1, a = -1$$

$$2c + 4d + 4 = 0$$

$$d + 2 = 0$$

$$d = -2, c = 2$$

The nullspace is made up of vectors

$$m \begin{bmatrix} -1 \\ -1 \\ 1 \\ 0 \end{bmatrix} + n \begin{bmatrix} 2 \\ -2 \\ 0 \\ 1 \end{bmatrix}$$

- A particular solution to $A\vec{x} = \vec{b}$ (where $\vec{b} = \begin{bmatrix} 4 \\ 3 \\ 5 \end{bmatrix}$) comes from

$$\left[\begin{array}{cccc|c} 2 & 4 & 6 & 4 & 4 \\ 0 & 1 & 1 & 2 & -1 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

We set free variables to 0 and solve

$$2x + 4y = 4$$

$$y = -1$$

$$x = 4$$

$$\vec{x}_p = \begin{bmatrix} 4 \\ -1 \\ 0 \\ 0 \end{bmatrix}$$

The complete solution is $\vec{x} = \begin{bmatrix} 4 \\ -1 \\ 0 \\ 0 \end{bmatrix} + m \begin{bmatrix} -1 \\ -1 \\ 1 \\ 0 \end{bmatrix} + n \begin{bmatrix} 2 \\ -2 \\ 0 \\ 1 \end{bmatrix}$

1) cont.

$$[U|c] = \left[\begin{array}{cccc|c} 2 & 4 & 6 & 4 & 4 \\ 0 & 1 & 1 & 2 & -1 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] \longrightarrow \left[\begin{array}{cccc|c} 1 & 2 & 3 & 2 & 2 \\ 0 & 1 & 1 & 2 & -1 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

$$\longrightarrow \left[\begin{array}{cccc|c} 1 & 0 & 1 & -2 & 4 \\ 0 & 1 & 1 & 2 & -1 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right] = [R|d].$$

6)

$$\begin{bmatrix} 1 & 2 \\ 2 & 4 \\ 2 & 5 \\ 3 & 9 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \end{bmatrix}.$$

$$\left[\begin{array}{cc|c} 1 & 2 & b_1 \\ 2 & 4 & b_2 \\ 2 & 5 & b_3 \\ 3 & 9 & b_4 \end{array} \right] \longrightarrow \left[\begin{array}{cc|c} 1 & 2 & b_1 \\ 0 & 0 & b_2 - 2b_1 \\ 0 & 1 & b_3 - 2b_1 \\ 0 & 3 & b_4 - 3b_1 \end{array} \right] \longrightarrow \left[\begin{array}{cc|c} 1 & 2 & b_1 \\ 0 & 0 & b_2 - 2b_1 \\ 0 & 1 & b_3 - 2b_1 \\ 0 & 0 & b_4 - 3b_1 - 3(b_3 - 2b_1) \end{array} \right]$$

So this is solvable when $b_2 - 2b_1 = 0$ and $b_4 - 3b_3 + 3b_1 = 0$.

In this case, $x_2 = b_3 - 2b_1$

$$x_1 + 2x_2 = b_1 \rightarrow x_1 = b_1 + 4b_1 - 2b_3$$

$$\text{So } \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 5b_1 - 2b_3 \\ b_3 - 2b_1 \end{bmatrix}.$$

$$\begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 2 & 5 & 7 \\ 3 & 9 & 12 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \end{bmatrix}$$

$$\left[\begin{array}{ccc|c} 1 & 2 & 3 & b_1 \\ 2 & 4 & 6 & b_2 \\ 2 & 5 & 7 & b_3 \\ 3 & 9 & 12 & b_4 \end{array} \right] \longrightarrow \left[\begin{array}{ccc|c} 1 & 2 & 3 & b_1 \\ 0 & 0 & 0 & b_2 - 2b_1 \\ 0 & 1 & 1 & b_3 - 2b_1 \\ 0 & 3 & 3 & b_4 - 3b_1 \end{array} \right] \longrightarrow \left[\begin{array}{ccc|c} 1 & 0 & 1 & b_1 - 2b_3 + 4b_1 \\ 0 & 0 & 0 & b_2 - 2b_1 \\ 0 & 1 & 1 & b_3 - 2b_1 \\ 0 & 0 & 0 & b_4 - 3b_1 - 3b_3 + 6b_1 \end{array} \right]$$

This is solvable when $b_2 - 2b_1 = 0$ and $b_4 - 3b_3 + 3b_1 = 0$.

Nullspace has special solution $\begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix}$, particular solution is $\begin{bmatrix} 5b_1 - 2b_3 \\ b_3 - 2b_1 \\ 0 \end{bmatrix}.$

$$\text{So } \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 5b_1 - 2b_3 \\ b_3 - 2b_1 \\ 0 \end{bmatrix} + C \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix}.$$

8) For a vector to be in the column space of A , we need to be able to solve $A\vec{x} = \vec{b}$.

$$a) A = \begin{bmatrix} 1 & 2 & 1 \\ 2 & 6 & 3 \\ 0 & 2 & 5 \end{bmatrix}$$

$$\left[\begin{array}{ccc|c} 1 & 2 & 1 & b_1 \\ 2 & 6 & 3 & b_2 \\ 0 & 2 & 5 & b_3 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & 2 & 1 & b_1 \\ 0 & 2 & 2 & b_2 - 2b_1 \\ 0 & 2 & 5 & b_3 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & 0 & -1 & 3b_1 - b_2 \\ 0 & 2 & 2 & b_2 - 2b_1 \\ 0 & 0 & 3 & b_3 - b_2 + 2b_1 \end{array} \right]$$

A has full row and full column rank and is invertible.

Thus, every vector in $\mathbb{R}^3$ is in the column space.

No combination of the rows of A is $\vec{0}$.

$$b) A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 4 \\ 2 & 4 & 8 \end{bmatrix}$$

$$\left[\begin{array}{ccc|c} 1 & 1 & 1 & b_1 \\ 1 & 2 & 4 & b_2 \\ 2 & 4 & 8 & b_3 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & 1 & 1 & b_1 \\ 0 & 1 & 3 & b_2 - b_1 \\ 0 & 2 & 6 & b_3 - 2b_1 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & 1 & 1 & b_1 \\ 0 & 1 & 3 & b_2 - b_1 \\ 0 & 0 & 0 & b_3 - 2b_2 \end{array} \right]$$

The column space of A consists of vectors $\begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$ with $b_3 = 2b_2$.

(Alternately, it is spanned by $\begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}$ and $\begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix}$.)

The combinations $0 \cdot (1, 1, 1) + -2c(1, 2, 4) + c(2, 4, 8)$ give the zero vector.

10) Construct $A\vec{x} = \vec{b}$ with $\vec{x}_p = (2, 4, 0)$, $x_n = \text{multiples of } (1, 1, 1)$.

Free variable = x_3

$$\begin{bmatrix} 1 & 0 & a \\ 0 & 1 & b \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = \vec{0} \rightarrow \begin{array}{l} a = -1 \\ b = -1 \end{array}$$

$$\text{So } A = \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \end{bmatrix} \text{ works}$$

Now we need $\vec{b}$, but $\vec{x}_p$ is a solution, so $\vec{b} = A\vec{x}_p$.

$$\begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} 2 \\ 4 \\ 0 \end{bmatrix} = \begin{bmatrix} 2 \\ 4 \end{bmatrix}$$

$$\text{So } A\vec{x} = \vec{b} \text{ is } \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 \\ 4 \end{bmatrix}$$

17) The largest possible rank of a 6 by 4 matrix is 4.

Then there is a pivot in every column of U and R .

The solution to $A\vec{x} = \vec{b}$ is unique.

The nullspace of A is zero.

An example is

$$A = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

24) a) $A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$ will give $A\vec{x} = \vec{b}$ with 0 or 1 solution, depending on $\vec{b}$.

b) ~~$A = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 2 \end{bmatrix}$~~ $A = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 2 \end{bmatrix}$ will give $A\vec{x} = \vec{b}$ with infinitely many solutions.

c) $A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$ will give $A\vec{x} = \vec{b}$ with 0 or ∞ solutions depending on $\vec{b}$.

d) $A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ will give $A\vec{x} = \vec{b}$ with 1 solution, regardless of $\vec{b}$.

§3.5

3) $U = \begin{bmatrix} a & b & c \\ 0 & d & e \\ 0 & 0 & f \end{bmatrix}.$

If $a=0$: $2 \cdot \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} + 0 \cdot \begin{bmatrix} b \\ d \\ 0 \end{bmatrix} + 0 \cdot \begin{bmatrix} c \\ e \\ f \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$, so columns of U are dependent.

If $d=0$: $b \cdot \begin{bmatrix} a \\ 0 \\ 0 \end{bmatrix} - a \cdot \begin{bmatrix} b \\ 0 \\ 0 \end{bmatrix} + 0 \cdot \begin{bmatrix} c \\ e \\ f \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$, so columns of U are dependent.

If $f=0$: $\left(\frac{ebcd}{a}\right) \begin{bmatrix} a \\ 0 \\ 0 \end{bmatrix} + e \cdot \begin{bmatrix} b \\ d \\ 0 \end{bmatrix} - d \begin{bmatrix} c \\ e \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ so columns of U are dependent.

10) $x + 2y - 3z - t = 0$ plane in $\mathbb{R}^4$.

Three independent vectors:

$$\begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ 2 \end{bmatrix}$$

There can't be four independent vectors in the plane because if there were, the plane would be all of $\mathbb{R}^4$. The plane has dimension 3.

$A = \begin{bmatrix} 1 & 2 & -3 & -1 \end{bmatrix}$ has this plane as its nullspace.

13) $A = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 3 & 1 \\ 3 & 1 & -1 \end{bmatrix}$ $U = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 0 \end{bmatrix}$

a) $\dim C(A) = 2$ (= rank).

b) $\dim C(U) = 2$ (= rank)

c) $\dim C(A^T) = 2$ (= rank)

d) $\dim C(U^T) = 2$ (= rank)

The row space of A and the row space of U are the same space.

22) S a 5-dim. subspace of $\mathbb{R}^6$.

a) Every basis of S can be extended to a basis for $\mathbb{R}^6$ by adding one vector. TRUE.

(Add any vector not in S).

b) Every basis for $\mathbb{R}^6$ can be reduced to a basis for S by deleting a vector. FALSE.

For example, $S = \left\{ \begin{bmatrix} 0 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \end{bmatrix} \right\}$

Then $\begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \\ 1 \\ 1 \end{bmatrix}$ form a basis for $\mathbb{R}^6$.
But none are in S ,
so deleting one
won't give a basis for S .

35) A basis for polynomials with degree ≤ 3 : $\boxed{1, x, x^2, x^3}$.

(Any poly. with degree ≤ 3 is a linear combo of these
 $ax^3 + bx^2 + cx + d$.)

and they are linearly independent since scalars are numbers, not x 's).

A basis for the subspace with $p(1)=0$:

If $p(1)=0$, then that means $a+b+c+d=0$ (for $p(x)=ax^3+bx^2+cx+d$).

Basis: $\boxed{x-1, x^2-x, x^3-x^2}$.

These are linearly independent:

If $a(x-1) + b(x^2-x) + c(x^3-x^2) = 0$, then

$$cx^3 + (b-c)x^2 + (a-b)x - a = 0, \text{ so}$$

all coefficients must be 0.

$$c=0$$

$$b-c=0$$

$$a-b=0$$

$$a=0$$

$$\left. \begin{array}{l} c=0 \\ b-c=0 \\ a-b=0 \\ a=0 \end{array} \right\} \Rightarrow b=0.$$

Thus, the only linear combo of these vectors that gives 0 is the combo with all coefficients equal to 0. This means the vectors are independent.

These vectors actually span the space:

Say $p(x) = ax^3 + bx^2 + cx + d$ is in the space
(so $a+b+c+d=0$).

$$\text{Then } a(x^3-x^2) + (a+b)(x^2-x) + (a+b+c)(x-1)$$

$$= ax^3 + bx^2 + cx + -(a+b+c).$$

Since $a+b+c+d=0$, $-(a+b+c)=d$, so in fact

$$a(x^3-x^2) + (a+b)(x^2-x) + (a+b+c)(x-1) = ax^3 + bx^2 + cx + d = p(x).$$

So the vectors span, and they do form a basis.

§ 3.6

$$2) A = \begin{bmatrix} 1 & 2 & 4 \\ 2 & 4 & 8 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 4 \\ 0 & 0 & 0 \end{bmatrix}$$

Column space: dimension = 1.
basis: $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$.

Row space: dimension = 1
basis: $(1, 2, 4)$.

Nullspace: dimension = 2.
basis: special solutions.

$$s_1 = \begin{bmatrix} a \\ 1 \\ 0 \end{bmatrix}, \quad s_2 = \begin{bmatrix} b \\ 0 \\ 1 \end{bmatrix}.$$

$$a + 2 = 0$$

$$b + 4 = 0$$

$$s_1 = \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}$$

$$s_2 = \begin{bmatrix} -4 \\ 0 \\ 1 \end{bmatrix}.$$

Left nullspace: dimension = 1.
basis: $(-2, 1)$.

$$B = \begin{bmatrix} 1 & 2 & 4 \\ 2 & 5 & 8 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & 4 \\ 0 & 1 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 4 \\ 0 & 1 & 0 \end{bmatrix}$$

Column space: dimension = 2.
basis: $\begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 5 \end{bmatrix}$.

Row space: dimension = 2
basis: $(1, 2, 4), (2, 5, 8)$.

Nullspace: dimension = 1
basis: $\begin{bmatrix} -4 \\ 0 \\ 1 \end{bmatrix}$.

Left nullspace: dimension = 0
basis: ~~empty set~~.
empty set.

$$14) A = \begin{bmatrix} 1 & 0 & 0 \\ 6 & 1 & 0 \\ 9 & 8 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 1 & 2 \end{bmatrix}$$

Column space: basis is $1^{st}, 2^{nd}, 3^{rd}$ columns of A , which are

$$\begin{bmatrix} 1 \\ 6 \\ 9 \end{bmatrix}, \begin{bmatrix} 2 \\ 13 \\ 26 \end{bmatrix}, \begin{bmatrix} 3 \\ 20 \\ 44 \end{bmatrix}$$

(Alternate, better solution:

$C(A)$ is $\dim. 3$ in $\mathbb{R}^3$, so it is all of $\mathbb{R}^3$.

Basis: $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$

Row space: basis is $(1, 2, 3, 4)$
 $(0, 1, 2, 3)$
 $(0, 0, 1, 2)$.

Nullspace: basis is special solution. $\begin{bmatrix} a \\ b \\ c \\ 1 \end{bmatrix}$

$$a + 2b + 3c + 4 = 0 \rightarrow a = 0$$

$$b + 2c + 3 = 0 \rightarrow b = 1$$

$$c + 2 = 0 \rightarrow c = -2$$

basis: $\begin{bmatrix} 0 \\ 1 \\ -2 \\ 1 \end{bmatrix}$

Left nullspace: basis: empty, since $\dim N(A^T) = 0$.

$$19) a) \begin{bmatrix} 1 & 2 & b_1 \\ 3 & 4 & b_2 \\ 4 & 6 & b_3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & b_1 \\ 0 & -2 & b_2 - 3b_1 \\ 0 & -2 & b_3 - 3b_1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & b_1 \\ 0 & -2 & b_2 - 3b_1 \\ 0 & 0 & b_3 - b_2 \end{bmatrix}$$

Basis for left nullspace: $(0, -1, 1)$.

$$b) \begin{bmatrix} 1 & 2 & b_1 \\ 2 & 3 & b_2 \\ 2 & 4 & b_3 \\ 2 & 5 & b_4 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & b_1 \\ 0 & -1 & b_2 - 2b_1 \\ 0 & 0 & b_3 - 2b_1 \\ 0 & 1 & b_4 - 2b_1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 2 & b_1 \\ 0 & -1 & b_2 - 2b_1 \\ 0 & 0 & b_3 - 2b_1 \\ 0 & 0 & b_4 + b_2 - 4b_1 \end{bmatrix}$$

Basis for left nullspace:

$$(-2, 0, 1, 0), (-4, 1, 0, 1).$$

24) $A^T y = d$ is solvable when d is in $C(A^T) = \text{row space of } A$.

The solution is unique when the left nullspace of $A = N(A^T)$ contains only the zero vector.

25) a) A and A^T have the same number of pivots.

TRUE. # pivots of $A = \text{rank of } A = \dim C(A) = \dim C(A^T)$.

pivots of $A^T = \text{rank of } A^T = \dim C(A^T) = \dim C((A^T)^T) = \dim C(A)$.

So A and A^T have the same number of pivots.

b) A and A^T have the same left nullspace

FALSE. For example, $A = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$, $A^T = \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix}$.

Then $(1, -1)$ is in ~~the~~ the left nullspace of A^T ,

but not in the left nullspace of A .

$(0, 1)$ is in the left nullspace of A , but not in the left nullspace of A^T .

c) If the row space = column space, then $A = A^T$.

FALSE. For example, $A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$, $A^T = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \neq A$.

But the row space of A is $\mathbb{R}^2$, and so is the column space. (they even have the same basis, $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$).

d) If $A^T = -A$, then the row space of A equals the column space.

TRUE. row space of $A = C(A^T) = C(-A)$ since $A^T = -A$.

But $C(A) = C(-A)$ since the columns of $-A$ are just the columns of A times a constant. Thus, any linear combination of columns of A can clearly be written as a linear combination of columns of $-A$ and vice versa.

So the row space of $A =$ the column space of A in this case.